



# **iZ-C Reference Manual**

*version 3.7*

**NTT DATA SEKISUI SYSTEMS**

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## CONTENTS:

<b>1</b>	<b>Preface</b>	<b>1</b>
<b>2</b>	<b>Execution Environment</b>	<b>3</b>
2.1	Initialize and Finalize . . . . .	3
2.2	Error status . . . . .	3
2.3	Error handler . . . . .	4
2.4	Version Information . . . . .	4
2.5	Output of Statistics Information . . . . .	4
<b>3</b>	<b>Domain variable and Basic functions</b>	<b>5</b>
3.1	Constructors . . . . .	5
3.2	Functions to Access Domain Variable . . . . .	5
3.3	Constraints for Domain . . . . .	7
<b>4</b>	<b>Arithmetic Constraints</b>	<b>9</b>
<b>5</b>	<b>Relation Constraints</b>	<b>11</b>
<b>6</b>	<b>High-level Constraints</b>	<b>13</b>
<b>7</b>	<b>Generation Mechanisms (Search) and Heuristics</b>	<b>15</b>
7.1	Basic Functions for Generation . . . . .	15
7.2	Pre-defined Choice Functions . . . . .	15
7.3	Number of Fails and Choice Points . . . . .	16
7.4	Sophisticated Generation Functions . . . . .	16
7.5	To Stop Search Functions . . . . .	19
7.6	Domain Reduction . . . . .	19
7.7	Management of NoGood . . . . .	22
7.8	Notifications of Search state . . . . .	23
<b>8</b>	<b>Demon</b>	<b>27</b>
<b>9</b>	<b>Context</b>	<b>29</b>
	<b>Index</b>	<b>31</b>



**PREFACE**

iZ is an efficient and extendable library for Constraint Solving. iZ is dedicated to expressing declaratively and solving complex combinatorial problems such as resource allocation, scheduling, planning or production control.

This manual is the reference of iZ-C (C language version of iZ), describing all the primitive functions available.

iZ-C is available from:

[http://www.constraint.org/en/izc\\_download.html](http://www.constraint.org/en/izc_download.html)



## EXECUTION ENVIRONMENT

### 2.1 Initialize and Finalize

`cs_init()` must be called before iZ-C API functions. And `cs_end()` must be called when before program is terminated.

void **cs\_init** (void)

Set up internal memory for iZ-C.

void **cs\_end** (void)

Memory that is implicitly allocated (CSint variable creation, constraint declaration, ...) between `cs_init()` and `cs_end()` is freed when `cs_end()` is called.

CSint variables should not be accessed after `cs_end()`.

### 2.2 Error status

iZ-C library has a variable to hold error status. Library user can check error by reading this variable. (This variable is called *err* in this manual.)

void **cs\_initErr** (void)

Internal *err* variable is initialized by calling `cs_initErr()`. (the value of *err* is set to `CS_ERR_NONE`).

`cs_initErr()` is called implicitly by `cs_init()`.

int **cs\_getErr** (void)

Returns current value of *err*. If it returns `CS_ERR_NONE`, it means there has been no error raised between the last `cs_getErr()` or `cs_init()` call and this `cs_getErr()` call.

*err* can be set following values:

**CS\_ERR\_NONE**

No error has been occurred.

**CS\_ERR\_GETVALUE**

`cs_getValue()` is called for non-instantiated variable.

**CS\_ERR\_OVERFLOW**

Overflow has been occurred.

**CS\_ERR\_NO\_MEMORY**

Cannot allocate memory.

void **cs\_setErr** (int *code*)

Set value of *err* to *code*.

## 2.3 Error handler

Function can be registered to handle error. Registered function will be called after *err* is set when error has occurred.

void **cs\_setErrorHandler** (int *code*, void (\**func*)(void\* data, void\* ext), void\* *ext*)

Register function *func* as error handler of *code*. Parameter *data* will have different value as *code* (see following table) and parameter *ext* is same value as *cs\_setErrorHandler* is called.

Code	Data	Default action
CS_ERR_GETVALUE	Pointer to CSint	Print message and process is continued.
CS_ERR_OVERFLOW	NULL	Do nothing and process is continued.
CS_ERR_NO_MEMORY	NULL	Call abort() (process will be terminated)

## 2.4 Version Information

const char\* **cs\_getVersion** (void)

Returns version string of iZ-C. (ex: "3.5.0")

This string is equivalent to which is concatenated these following values using ".".

**IZ\_VERSION\_MAJOR**

Major version of iZ-C

**IZ\_VERSION\_MINOR**

Minor version of iZ-C

**IZ\_VERSION\_PATCH**

Patch level of iZ-C

## 2.5 Output of Statistics Information

void **cs\_printStats** (void)

Print statistics values:

- Nb Fails (the number of fails that occurred during the generation process)
- Nb Choice Points (the number of instantiations on which it is possible to backtrack)
- Heap Size (the size of the heap which saves the context to enable backtrack).

Nb Fails and Nb Choice Points can be accessed directly using the `cs_getNbFails()` and `cs_getNbChoicePoints()`.

void **cs\_fprintStats** (FILE \**f*)

It is similar to *cs\_printStats*() except that it takes a pointer to FILE as an argument, and writes to the indicated file when the function is invoked.

## DOMAIN VARIABLE AND BASIC FUNCTIONS

A CSint is an integer domain variable. Only pointers to CSint (CSint\*) are used in the pre-defined iZ functions.

### 3.1 Constructors

CSint variables can be constructed by these following functions:

CSint \***cs\_createCSint** (int *min*, int *max*)

Creates a CSint variable whose domain is { *min* .. *max* }.

CSint \***cs\_createNamedCSint** (int *min*, int *max*, char \**name*)

Creates a CSint variable whose domain is { *min* .. *max* }, and associates a name to it. (It is equivalent to *cs\_createCSint()* followed by *cs\_setName()*.)

CSint \***CSINT** (int *n*)

Creates an already instantiated (i.e. its domain is reduced to one element) CSint variable. This function is equivalent to *cs\_createCSint(n, n)*.

CSint \***cs\_createCSintFromDomain** (int \**array*, int *size*)

Creates a CSint variable its domain is defined by the *array* (of *size* integers).

CSint \*\***cs\_createCSintArray** (int *nbVars*, int *min*, int *max*)

Creates an array of *nbVars* CSint variables, which all have the same { *min* .. *max* } domain.

<note>This function returns pointer to array of CSint pointers. Don't call free() for this array because array is managed by iZ-C.

### 3.2 Functions to Access Domain Variable

Following basic functions give access to CSint (a domain variable):

int **cs\_getMin** (CSint \**vint*)

Returns the minimum value of the domain of *vint*.

int **cs\_getMax** (CSint \**vint*)

Returns the maximum value of the domain of *vint*.

int **cs\_getNbElements** (CSint \**vint*)

Returns the number of elements in the domain of *vint*.

int **cs\_getNbConstraints** (CSint \**vint*)

Returns the number of constraints *vint* is involved in. (Constraints which failed when setting are not included.)

char \***cs\_getName** (CSint \**vint*)

Returns the name of *vint* (which has been set using `cs_setName()`). The name of a CSint variable can also be displayed by using the “%T” format conversion string of the `cs_printf()` or `cs_fprintf()` functions.

int **cs\_getNextValue** (CSint \**vint*, int *val*)

Returns the first element in the domain of *vint* which is strictly greater than *val*. If *val* is greater than `cs_getMax(vint)`, then it returns INT\_MAX (the maximum value of an int).

In the following code, `cs_getNextValue()` is used as an expression of a ‘for’ statement:

```
void display(CSint *vint)
{
    int val;
    for (val = cs_getMin(vint); val <= cs_getMax(vint); val = cs_getNextValue(vint,
↪val))
        printf("%d ", val);
}
```

The `display()` function defined above will print on the stdout file all the possible values of a CSint variable (i.e. its domain) in increasing order.

int **cs\_getPreviousValue** (CSint \**vint*, int *val*)

Returns the first element in the domain of *vint* which is strictly lower than *val*. If *val* is lower than `cs_getMin(vint)`, then it returns INT\_MIN (the minimum value of an int).

int \***cs\_getDomain** (CSint \**vint*)

Returns an array of `cs_getNbElements( vint )` elements whose values are the elements of the domain of *vint*. (Returned array should be ‘free’ed by user)

void **cs\_freeDomain** (int\* *array*)

Free *array* allocated by `cs_getDomain()`.

IZBOOL char **cs\_isIn** (CSint \**vint*, int *val*)

Returns TRUE if *val* is an element of the domain of *vint*. Otherwise it returns FALSE.

void **cs\_setName** (CSint \**vint*, char \**name*)

Associate a *name* to a CSint variable *vint*. When the *vint* will be displayed (using `cs_printf()` or `cs_fprintf()`), its associated name can also be displayed (if the format “%T” is specified).

IZBOOL **cs\_isFree** (CSint \**vint*)

Returns TRUE if *vint* is not yet instantiated (i.e. `cs_getNbElements( vint ) > 1`, i.e. `cs_getMin( vint ) < cs_getMax( vint )`). Otherwise returns FALSE.

IZBOOL char **cs\_isInstantiated** (CSint \**vint*)

Returns TRUE if *vint* is instantiated (i.e. `cs_getNbElements( vint ) == 1`, i.e. `cs_getMin( vint ) == cs_getMax( vint )`). Otherwise returns FALSE.

int **cs\_getValue** (CSint \**vint*)

Returns the value of *vint* in case *vint* has been instantiated. An error occurs (i.e. a call to `cs_getErr()` returns CS\_ERR\_GETVALUE) if *vint* has not been instantiated yet, and `cs_getValue( vint )` returns `cs_getMin( vint )`.

void **cs\_printf** (const char \**control*, ...)

Is similar to the standard `printf()` C function except that three new conversion characters dedicated to CSint variables and CSint variable arrays has been added:

- `cs_printf("%T", vint)` prints the name of *vint* (if it has one) followed by its domain.
- `cs_printf("%D", vint)` prints only the domain of *vint* on the standard output file, stdout.
- `cs_printf("%A", array, size)` prints the array of CSint variables (with their name, if any) array, of size elements, separated by a comma.

void **cs\_fprintf** (FILE \**f*, const char \**control*, ...)

It is similar to `cs_printf()` except that it takes a pointer to FILE as an argument, and writes to the indicated file when the function is invoked.

### 3.3 Constraints for Domain

Following functions are constraints, and may fail (i.e. return a FALSE value) when posted:

IZBOOL **cs\_InArray** (CSint \**vint*, int \**array*, int *size*)

Constrains the domain of CSint variable *vint* to be the domain contained in the *array* .

IZBOOL **cs\_NotInArray** (CSint \**vint*, int \**array*, int *size*)

Constrains the CSint variable *vint* not to have the values in the *array* . All the values of the domain of *vint* that are in *array* are removed.

It could be defined as:

```
IZBOOL cs_notInArray(CSint *vint, int *array, int size) {
    int i;
    for (i = 0; i < size; i++)
        if (!cs_NEQ(vint, array[i])
            return FALSE;

    return TRUE;
}
```

IZBOOL **cs\_InInterval** (CSint \**vint*, int *min*, int *max*)

Constrains the CSint variable *vint* to be { *min* .. *max* } (i.e. `cs_getMin(vint) >= min` and `cs_getMax(vint) <= max`).

It could be defined as:

```
IZBOOL cs_InInterval(CSint *vint, int min, int max) {
    return (cs_GE(vint, min) && cs_LE(vint, max));
}
```

IZBOOL **cs\_NotInInterval** (CSint \**vint*, int *min*, int *max*)

Constrains the CSint variable *vint* not to have the values in { *min* .. *max* }. All the values of the domain of *vint* that are in {*min*..*max*} are removed.

It could be defined as:

```
IZBOOL cs_NotInInterval(CSint *vint, int min, int max) {
    int i;
    for (i = min; i <= max; i++)
        if (!cs_NEQ(vint, i))
            return FALSE;

    return TRUE;
}
```



## ARITHMETIC CONSTRAINTS

These constraints enable the user to create a new CSint variable defined by arithmetic relations between already existing CSint variables. These constraints never fails when the user posts it.

CSint \***cs\_Add** (CSint \**vint1*, CSint \**vint2*)

Returns a CSint variable defined as the sum of *vint1* and *vint2* .

CSint \***cs\_VAdd** (int *nbVars*, CSint \**vint*, ...)

*cs\_VAdd*() accepts a variable number of arguments (number specified by the first argument *nbVars* ).

It returns a CSint variable defined as the sum of the CSint variables given in arguments.

$$cs\_VAdd(n, V1, V2, \dots, Vn) = V1 + V2 + \dots + Vn$$

CSint \***cs\_Sub** (CSint \**vint1*, CSint \**vint2*)

Returns a CSint variable defined as the difference between *vint1* and *vint2* .

CSint \***cs\_VSub** (int *nbVars*, CSint \**vint*, ...)

*cs\_VSub*() accepts a variable number of arguments (number specified by the first argument *nbVars* ).

It returns a CSint variable defined as the difference between the first argument and the sum of all the others.

$$cs\_VSub(n, V1, V2, V3, \dots, Vn) = V1 - V2 - V3 - \dots - Vn$$

CSint \***cs\_Mul** (CSint \**vint1*, CSint \**vint2*)

Returns a CSint variable defined as the product of *vint1* and *vint2* .

CSint \***cs\_VMul** (int *nbVars*, CSint \**vint*, ...)

*cs\_VMul*() accepts a variable number of arguments (number specified by the first argument *nbVars* ).

It returns a CSint variable defined as the product of the CSint variables given in arguments.

$$cs\_VMul(n, V1, V2, \dots, Vn) = V1 * V2 * \dots * Vn$$

CSint \***cs\_Div** (CSint \**vint1*, CSint \**vint2*)

Returns a CSint variable defined as the quotient of *vint1* and *vint2* .

CSint \***cs\_VDiv** (int *nbVars*, CSint \**vint*, ...)

*cs\_VDiv*() accepts a variable number of arguments (number specified by the first argument *nbVars* ).

CSint \***cs\_Sigma** (CSint \*\**array*, int *size*)

Returns a CSint variable constrained to be equal to the sum of the *size* CSint variables referenced by *array*.

CSint \***cs\_ScalProd** (CSint \*\**array*, int \**vector*, int *size*)

Returns a CSint variable constrained to be equal to the scalar product of the vector of CSint variables *array* and the vector of integer *vector* (both of *size* elements).

CSint \***cs\_VScaProd** (int *nbVars*, CSint \**vint*, ...)

*cs\_VScaProd*() accepts a variable number of arguments (number specified by the first argument *nbVars* ).

`cs_VScalProd(n, V1, V2, ..., Vn, c1, c2, ..., cn)` returns the scalar product of the vector of CSint variables ( $V1, V2, \dots, Vn$ ) and the vector of integer ( $c1, c1, \dots, cn$ ).

CSint \***cs\_Abs** (CSint \**vinc*)

Returns a CSint variable constrained to be equal to the absolute value of the CSint variable *vinc* .

## RELATION CONSTRAINTS

The following functions set constraints between already existing CSint variables. These functions may fail (i.e. return a FALSE value) when set.

IZBOOL **cs\_Le** (CSint \*vint1, CSint \*vint2)  
vint1 must be lower than or equal to vint2 (i.e. cs\_getMin(vint1) <= cs\_getMin(vint2) and cs\_getMax(vint1) <= cs\_getMax(vint2)).

IZBOOL **cs\_Ge** (CSint \*vint1, CSint \*vint2)  
vint1 must be greater than or equal to vint2.

IZBOOL **cs\_Lt** (CSint \*vint1, CSint \*vint2)  
vint1 must be strictly lower than vint2.

IZBOOL **cs\_Gt** (CSint \*vint1, CSint \*vint2)  
vint1 must be strictly greater than vint2.

IZBOOL **cs\_Eq** (CSint \*vint1, CSint \*vint2)  
vint1 and vint2 are constrained to be equal.

IZBOOL **cs\_Neq** (CSint \*vint1, CSint \*vint2)  
vint1 and vint2 are constrained not to be equal.

The following similar functions are useful when one of the two operands is a constant:

- IZBOOL cs\_LE (CSint \*vint, int val)
- IZBOOL cs\_GE (CSint \*vint, int val)
- IZBOOL cs\_LT (CSint \*vint, int val)
- IZBOOL cs\_GT (CSint \*vint, int val)
- IZBOOL cs\_EQ (CSint \*vint, int val)
- IZBOOL cs\_NEQ (CSint \*vint, int val)

For example, cs\_LE() could be defined as:

```
IZBOOL cs_LE(CSint *vint, int val) {  
    return(cs_Le(vint, CSINT(val)));  
}
```

IZBOOL **cs\_AllNeq** (CSint \*\*array, int size)

The CSint variables of array must have different values. It could be written like:

```
IZBOOL cs_AllNeq(CSint **array, int size) {  
    int i, j;  
    for (i = 0; i < size - 1; i++)
```

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```
for (j = i + 1; j < size; j++)  
    cs_Neq(array[i], array[j]);  
}
```

The following functions return CSint variable which indicates whether relation constraint is satisfied or not. (satisfied = 1, NOT satisfied = 0)

CSInt\* **cs\_ReifLe** (CSint \*vint1, CSint \*vint2)

Returns a CSint variable which indicates whether vint1 is lower than or equal to vint2 by value 1 and 0.

CSInt\* **cs\_ReifGe** (CSint \*vint1, CSint \*vint2)

Returns a CSint variable which indicates whether vint1 is greater than or equal to vint2 by value 1 and 0.

CSInt\* **cs\_ReifLt** (CSint \*vint1, CSint \*vint2)

Returns a CSint variable which indicates whether vint1 is lower than vint2 by value 1 and 0.

CSInt\* **cs\_ReifGt** (CSint \*vint1, CSint \*vint2)

Returns a CSint variable which indicates whether vint1 is greater than vint2 by value 1 and 0.

CSInt\* **cs\_ReifEq** (CSint \*vint1, CSint \*vint2)

Returns a CSint variable which indicates whether vint1 is equal to vint2 by value 1 and 0.

CSInt\* **cs\_ReifNeq** (CSint \*vint1, CSint \*vint2)

Returns a CSint variable which indicates whether vint1 is different from vint2 by value 1 and 0.

The following functions are useful when second CSint variable is a constant:

- CSInt\* cs\_ReifLE(CSint \*vint, int val)
- CSInt\* cs\_ReifGE(CSint \*vint, int val)
- CSInt\* cs\_ReifLT(CSint \*vint, int val)
- CSInt\* cs\_ReifGT(CSint \*vint, int val)
- CSInt\* cs\_ReifEQ(CSint \*vint, int val)
- CSInt\* cs\_ReifNEQ(CSint \*vint, int val)

## HIGH-LEVEL CONSTRAINTS

These following constraints are more complex ones. They could be written using the previous primitives and *demon* (see *Demon*).

Constraint functions which return CSint variable can return NULL to indicate fail.

IZBOOL **cs\_IfEq** (CSint \*vint1, CSint \*vint2, int val1, int val2)

If *vint1* is instantiated to the value *val1* , then *vint2* will be instantiated to *val2* .

If *vint2* is instantiated to the value *val2* , then *vint1* will be instantiated to *val1* .

IZBOOL **cs\_IfNeq** (CSint \*vint1, CSint \*vint2, int val1, int val2)

The couple of CSint variables ( *vint1* , *vint2* ) cannot have the values ( *val1* , *val2* ).

CSint \***cs\_Occur** (CSint \*vint, int val, CSint \*\*array, int size)

The value *val* must appear *vint* times in the *array* .

This function is deprecated and will be deleted in future version. Please use *cs\_OccurConstraints()* .

CSint \***cs\_OccurDomain** (int val, CSint \*\*array, int size)

Returns CSint variable which counts the value *val* in the *array* .

IZBOOL **cs\_OccurConstraints** (CSint \*vint, int val, CSint \*\*array, int size)

The value *val* must appear *vint* times in the *array* .

CSint \***cs\_Index** (CSint \*\*array, int size, int val)

Returns CSint variable *index* which is constrained *array* [ *index* ] = *val* .

$i \in \text{domain}( \textit{index} ) \Leftrightarrow \textit{val} \in \text{domain}( \textit{array} [ i ] )$

CSint \***cs\_Element** (CSint \*index, int \*values, int size)

Returns CSint variable *element* which is constrained *element* = *values* [ *index* ] .

CSint \***cs\_VarElement** (CSint \*index, CSint \*\*array, int size)

Returns CSint variable *element* which is constrained *element* = *array* [ *index* ] .

CSint \***cs\_VarElementRange** (CSint \*index, CSint \*\*array, int size)

Constraints CSint variables like *cs\_VarElement()* . But constraint propagation for variables in *array* will occur only when upper or lower bound is changed.

CSint \***cs\_Min** (CSint \*\*array, int size)

Returns a CSint variable equal to the minimum of the CSint variables referenced by *array* .

CSint \***cs\_VMin** (int nbVars, CSint \*vint, ...)

*cs\_VMin()* accepts a variable number of arguments (number specified by the first argument *nbVars* ).

CSint \***cs\_Max** (CSint \*\*array, int size)

Returns a CSint variable equal to the maximum of the CSint variables referenced by *array* .

CSint \***cs\_VMax** (int *nbVars*, CSint \**vint*, ...)

*cs\_VMax*() accepts a variable number of arguments (number specified by the first argument *nbVars* ).

IZBOOL **cs\_Cumulative** (CSint\*\* *startVars*, CSint\*\* *durationVars*, CSint\*\* *resourceVars*, int *size*, CSint\* *limitVar*)

This constraint is mainly used in scheduling problems. Task *i* in *size* tasks starts at *startVars* [*i*], duration is *durationVars* [*i*] and uses resource *resourceVars* [*i*].

Amount of resource used by Tasks running simultaneously is constrained not to exceed *limitVar*.

IZBOOL **cs\_Disjunctive** (CSint\*\* *startVars*, CSint\*\* *durationVars*, int *size*)

This constraint is mainly used in scheduling problems. Task *i* in *size* tasks starts at *startVars* [*i*] and duration is *durationVars* [*i*].

All tasks are constrained not to run simultaneously.

IZBOOL **cs\_Regular** (CSint\*\* *array*, int *size*, const int\* *d*, int *Q*, int *S*, int *q0*, const int\* *F*, int *fsize*)

The array of CSint variables referenced by *array* is constrained to be sequence of symbols which accepted by automaton defined by *d*, *Q*, *S*, *q0*, *F*.

- *d* is the array of integer sized  $Q \times S$ . Transitions in state *q* and input *s* are stored at  $q \times S + s$ . (-1 means 'not accepted')
- *Q* is the number of states.
- *S* is the number of symbols.
- *q0* is the initial state.
- *F* is the array (length *fsize*) of accepting states.

## GENERATION MECHANISMS (SEARCH) AND HEURISTICS

After the constraints have been posted, one may want to try to find a solution satisfies all constraints.

The basic principle of generation (called “search”) is:

1. Find a free CSint variable *var* among *allvars*. Search is end if there is no free variable (all variables are already instantiated).
2. Reduce the domain of variable *var*. For example, select a value *val* in the domain of *var* and try to instantiate: `cs_EQ(var, val)`.
  - If failed to reduce variable, then go to step 2 and try to reduce in another way. For example, select another value *val2* and instantiate selected variable.
  - If it succeeded, then go to step 1.

### 7.1 Basic Functions for Generation

IZBOOL **cs\_search** (CSint \*\**allvars*, int *nbVars*, CSint\* (\**findFreeVar*)(CSint \*\**allvars*, int *nbVars*))

This function tries to instantiate all the CSint variables referenced by *allvars*. It may fail if there is no solution.

The *findFreeVar* function finds a non-instantiated CSint variable among *allvars*.

IZBOOL **cs\_vsearch** (int *nbVars*, CSint \**vint*, ...)

*cs\_vsearch()* accepts a variable number of arguments (number specified by the first argument *nbVars* ).

### 7.2 Pre-defined Choice Functions

CSint \***cs\_findFreeVar** (CSint \*\**allvars*, int *nbVars*)

The first non-instantiated CSint variable in *allvars* is returned.

CSint \***cs\_findFreeVarNbElements** (CSint \*\**allvars*, int *nbVars*)

The non-instantiated CSint variable which has the lowest number of elements in its domain is returned.

CSint \***cs\_findFreeVarNbElementsMin** (CSint \*\**allvars*, int *nbVars*)

Among the CSint variables which all have the same lowest number of elements, it returns the one with the lowest minimum domain.

CSint \***cs\_findFreeVarNbConstraints** (CSint \*\**allvars*, int *nbVars*)

The non-instantiated CSint variable which is involved in the greatest number of constraints is returned.

For example, *cs\_findFreeVarNbElements()* could be defined as:

```
CSint *cs_findFreeVarNbElements(CSint **allvars, int nbVars) {
    int i;
    int nbElements, nbElementsOpt;
    CSint *varOpt = NULL;

    nbElementsOpt = INT_MAX;
    for (i = 0; i < nbVars; i++) {
        nbElements = cs_getNbElements(allvars[i]);
        if ((nbElements > 1) && (nbElements < nbElementsOpt)) {
            nbElementsOpt = nbElements;
            varOpt = allvars[i];
        }
    }
    return (varOpt);
}
```

## 7.3 Number of Fails and Choice Points

One can define heuristics that may depend on the number of Fails or the number of Choice Points that have occurred, using these functions:

int **cs\_getNbFails** ()

Returns the number of Fails that have occurred until this call. Functions that manage this parameter are:

- `cs_search()`
- `cs_searchFail()`
- `cs_Vsearch()`
- `cs_searchCriteria()`
- `cs_searchCriteriaFail()`
- `cs_searchValueSelectorFail()`
- `cs_searchValueSelectorRestartNG()`
- `cs_searchMatrix()`
- `cs_searchMatrixFail()`
- `cs_findAll()`
- `cs_minimize()`

int **cs\_getNbChoicePoints** ()

Returns the number of Choice Points that have been raised until this call. Functions that manage this parameter are same as `cs_getNbFails()`.

## 7.4 Sophisticated Generation Functions

IZBOOL **cs\_searchCriteria** (CSint \*\*allvars, int nbVars, int (\*findFreeVar)(CSint \*\*allvars, int nbVars), int (\*criteria)(int index, int val))

In `cs_search()`, when a CSint variable *var* has been chosen, the values are tried in increasing order (from `cs_getMin(var)` to `cs_getMax(var)`), avoiding all the values which are not in the domain of *var*).

`cs_searchCriteria()` enables to control this selection order. The value which minimize *criteria()* will be selected first.

IZBOOL **cs\_searchMatrix** (CSint \*\*\**matrix*, int *NbRows*, int *NbCols*, int (\**findFreeRow*)(CSint \*\*\**matrix*, int *NbRows*, int *NbCols*), int (\**findFreeCol*)(int row, CSint \*\**Row*, int *NbCols*), int (\**criteria*)(int row, int col, int val))

`cs_search()` and `cs_searchCriteria()` are used to generate a vector of CSint variables.

`cs_searchMatrix()` does the same for a matrix. `findFreeRow()` returns the index of the Row the user wants to chose. After a row has been chosen, `findFreeCol()` returns the index of the Col to be chosen. After a CSint variable (Col, Row) has been chosen, a value which minimize *criteria()* is selected.

IZBOOL **cs\_searchFail** (CSint \*\**allvars*, int *nbVars*, CSint\* (\**findFreeVar*)(CSint \*\**allvars*, int *nbVars*), int *NbFailsMax*)

`cs_searchFail()` is similar to `cs_search()` except that it stops, and return FALSE (i.e. fails) if the number of backtracks reaches *NbFailsMax*.

One can check if the fail has occurred because of the number of backtracks by checking *NbFails* (cf. `cs_getNbFails()` function).

IZBOOL **cs\_searchCriteriaFail** (CSint \*\**allvars*, int *nbVars*, int (\**findFreeVar*)(CSint \*\**allvars*, int *nbVars*), int (\**criteria*)(int index, int val), int *NbFailsMax*)

`cs_searchCriteriaFail()` is similar to `cs_searchCriteria()` except that it stops, and return FALSE (i.e. fails) if the number of backtracks reaches *NbFailsMax*.

One can check if the fail has occurred because of the number of backtracks by checking *NbFails* (cf. `cs_getNbFails()` function).

IZBOOL **cs\_searchValueSelectorFail** (CSint\*\* *allvars*, const CSvalueSelector\*\* *selectors*, int *nbVars*, int (\**findFreeVar*)(CSint\*\* *allvars*, int *nbVars*), int *NbFailsMax*, const CSsearchNotify\* *notify*)

`cs_searchValueSelectorFail()` tries to reduce domain of CSint variable using method specified by *selectors*. *selectors* is a array of pointer to CSvalueSelector variable which was created by `cs_getValueSelector()` or `cs_createValueSelector()`. This array must has *nbVars* elements.

*NbFailsMax* is treated as maximum fails like `cs_searchFail()`.

*notify* is a CSsearchNotify type variable to set notification functions. (see `cs_createSearchNotify()`) *notify* can be NULL If functionality is not needed.

IZBOOL **cs\_searchValueSelectorRestartNG** (CSint\*\* *allvars*, const CSvalueSelector\*\* *selectors*, int *nbVars*, int (\**findFreeVar*)(CSint\*\* *allvars*, int *nbVars*), int (\**maxFailFunction*)(void\* *state*), void\* *maxFailState*, int *nbFailsMax*, CSnoGoodSet\* *ngs*, const CSsearchNotify\* *notify*)

`cs_searchValueSelectorRestartNG()` is similar to `cs_searchValueSelectorFail()` but restart and NoGood is added.

At first, search is executed using returned value of *maxFailFunction* as a maximum fail count. If solution is not found, *maxFailFunction* is called again to get new maximum fail count and search is executed again.

*maxFailState* is passed to *maxFailFunction* as a parameter.

Failed variable-value combination (NoGood) is recored in *ngs* which is created by `cs_createNoGoodSet()` to avoid same failure. (By limitatin of space and time, not all NoGoods are recorded.)

*notify* is a CSsearchNotify type variable to set notification functions. (see `cs_createSearchNotify()`)

*ngs* and *\*notify* can be NULL If functionality is not needed.

Typically, `cs_searchValueSelectorRestartNG()` is called like following:

```

static int findFreeVarIndex(CSint **allvars, int nbVars) {
    for (int i = 0; i < nbVars; i++) {
        if (cs_isFree(allvars[i]))
            return i;
    }

    return -1;
}

static int nextFail(void* state) {
    int* pn = (int*)state;
    int ret = *pn;

    *pn = ret + 10;

    return ret;
}

/* ... */
const CSvalueSelector** vs = malloc(sizeof(CSvalueSelector*) * nbVars);
CSnoGoodSet* ngs = cs_createNoGoodSet(allvars, nbVars, NULL, 0, NULL, NULL);
CSsearchNotify* notify = cs_createSearchNotify(NULL);

int fail = 10;

for (int i = 0; i < nbVars; i++) {
    vs[i] = cs_getValueSelector(CS_VALUE_SELECTOR_MIN_TO_MAX);
}

cs_searchValueSelectorRestartNG(allvars, vs, nbVars, findFreeVarIndex,
↪nextFail, &fail, 100000, ngs, notify);
/* ... */

```

IZBOOL **cs\_searchMatrixFail** (CSint \*\*\*matrix, int NbRows, int NbCols, int (\*findFreeRow)(CSint \*\*\*matrix, int NbRows, int NbCols), int (\*findFreeCol)(int row, CSint \*\*Row, int NbCols), int (\*criteria)(int row, int col, int val), int NbFailsMax)

*cs\_searchMatrixFail()* is similar to *cs\_searchMatrix()* except that it stops, and return FALSE (i.e. fails) if the number of backtracks reaches *NbFailsMax*.

One can check if the fail has occurred because of the number of backtracks by checking *NbFails* (cf. *cs\_getNbFails()* function).

IZBOOL **cs\_findAll** (CSint \*\*allvars, int nbVars, CSint\* (\*findFreeVar)(CSint \*\*allvars, int nbVars), void (\*found)(CSint \*\*allvars, int nbVars))

Search for all possible solutions. Each time a solution is found, the *found()* function is called.

Typically, the *found()* function can be used to display the solutions:

```

void found(CSint **allvars, int nbVars) {
    static NbSolutions = 0;
    printf("Solution %d\n", ++NbSolutions);
    cs_printf("%A\n", allvars, nbVars);
}

```

IZBOOL **cs\_minimize** (CSint \*\*allvars, int nbVars, CSint\* (\*findFreeVar)(CSint \*\*allvars, int nbVars), CSint \*cost, void (\*found)(CSint \*\*allvars, int nbVars, CSint \*cost))

Try to find a solution minimizing the cost. At each step of the minimization, the *found()* function is called.

Typically, the found function can be used to display the current solution:

```
void found(CSint **allvars, int nbVars, CSint *cost) {

    static NbSolutions = 0;

    printf("Solution %d\n", ++NbSolutions);
    cs_printf("%A\n", allvars, nbVars);
    cs_printf("Cost = %T\n\n", cost);
}
```

`cs_minimize()` could be defined as:

```
IZBOOL cs_minimize(CSint **allvars, int nbVars, CSint* (*findFreeVar)(CSint_
↪**allvars, int nbVars), CSint *cost, void (*found)(CSint **allvars, int nbVars,
↪ CSint *cost)) {
    char gFirst, g;
    gFirst = g = cs_search(allvars, nbVars, findFreeVar);
    while (g) {
        int currentCost = getMin(cost);
        found(allvars, nbVars, cost);
        cs_restoreAll();
        g = (cs_LT(cost, currentCost) && cs_search(allvars, nbVars, findFreeVar));
    }
    return gFirst;
}
```

## 7.5 To Stop Search Functions

void **cs\_cancelSearch** (void)

Stop search at safe place. This function may be called from different thread from the thread search is running. Context may need to be restored using `cs_restoreContextUntil()`.

## 7.6 Domain Reduction

Following search functions takes CSvalueSelector type variables as paramter and can reduce a domain using various methods.

- `cs_searchValueSelectorFail()`
- `cs_searchValueSelectorRestartNG()`

### 7.6.1 Pre-defined Methods for Domain Reduction

const CSvalueSelector\* **cs\_getValueSelector** (int vs)

Get pre-defined CSvalueSelector instance. Following values can be specified as vs .

**CS\_VALUE\_SELECTOR\_MIN\_TO\_MAX**

Try single values in domain from minimum to maximum.

**CS\_VALUE\_SELECTOR\_MAX\_TO\_MIN**

Try single values in domain from maximum to minimum.

**CS\_VALUE\_SELECTOR\_LOWER\_AND\_UPPER**

Split domain using average of minimum and maximum value. Try lower half (including split value) and try rest of domain.

**CS\_VALUE\_SELECTOR\_UPPER\_AND\_LOWER**

Split domain using average of minimum and maximum value. Try upper half (including split value) and try rest of domain.

**CS\_VALUE\_SELECTOR\_MEDIAN\_AND\_REST**

Try median value of domain and try to remove that value.

## 7.6.2 User Defined Domain Reduction

Method for domain reduction can be defined by user. To define method for domain reduction, create `CSvalueSelector` type variable via `cs_createValueSelector()` and return `CSvalueSelection` type variable to generation function.

```
CSvalueSelector* cs_createValueSelector (IZBOOL (*init)(int index, CSint** vars, int size, void*
                                          pData), IZBOOL (*next)(CSvalueSelection* r, int index,
                                          CSint** vars, int size, void* pData), IZBOOL (*end)(int
                                          index, CSint** vars, int size, void* pData))
```

Define method for domain reduction as `CSvalueSelector` type variable. *init*, *next*, *end* are pointer to functions used to initialize(i.e constructor), enumerate, finalize(i.e destructor) respectively.

- *init* (function called once before domain reduction of a variable)
  - *index* : Index of variable in *vars*
  - *vars* : Array of `CSint` variables
  - *size* : Size of *vars*
  - *pData* : Pointer to arbitrary data can store pointer or int
  - return value: TRUE if success
- *next* (function to enumerate domain reduction of a variable)
  - *r* : Pointer to `CSvalueSelection` type variable to set domain reduction.
  - *index* : Index of variable in *vars*
  - *vars* : Array of `CSint` variables
  - *size* : Size of *vars*
  - *pData* : Pointer to arbitrary data can store pointer or int
  - return value: TRUE if valid *r* is set.
- *end* (function called once after all domain reductions of a variable are done)
  - *index* : Index of variable in *vars*
  - *vars* : Array of `CSint` variables
  - *size* : Size of *vars*
  - *pData* : Pointer to arbitrary data can store pointer or int. If malloc-ed memory is pointed by this variable, it must be free-ed in *end* function.
  - return value: TRUE if success

Returned `CSvalueSelector` type variable must be released by calling `cs_freeValueSelector()` after used.

void **cs\_freeValueSelector** (CSvalueSelector\* vs)  
 Release CSvalueSelector type variable created by *cs\_createValueSelector()*.

### 7.6.3 Functions and Types Related to Domain Reduction

#### CSvalueSelection

CSvalueSelection type describes how to reduce a domain of variable. It is defined as:

```
typedef struct {
    int method;
    int value;
} CSvalueSelection;
```

**method** means how to reduce a domain using *value* stored in **value**.

**method** field is used as described below:

#### CS\_VALUE\_SELECTION\_EQ

Select a *value* form a domain.

#### CS\_VALUE\_SELECTION\_NEQ

Remove a *value* form a domain.

#### CS\_VALUE\_SELECTION\_LE

Select range less than or equal to *value*

#### CS\_VALUE\_SELECTION\_LT

Select range less than *value*

#### CS\_VALUE\_SELECTION\_GE

Select range greater than or equal to *value*

#### CS\_VALUE\_SELECTION\_GT

Select range greater than *value*

IZBOOL **cs\_initValueSelector** (const CSvalueSelector\* vs, int *index*, CSint\*\*vars, int *size*, void\* *pData*)

Prepare to reduce a domain of CSint variable at *index* in array *vars* having *size* elements. *pData* is pointer to arbitrary data can store pointer or int.

Returns TRUE if succeeded.

IZBOOL **cs\_selectNextValue** (CSvalueSelection\* *r*, const CSvalueSelector\* vs, int *index*, CSint\*\* *vars*, int *size*, void\* *pData*)

Try to get domain reduction into *vs* for CSint variable at *index* in array *vars* having *size* elements. *pData* is pointer to arbitrary data can store pointer or int.

Returns TRUE if succeeded to store domain reduction into *vs*. Returns FALSE when all domain reductions is already enumerated.

IZBOOL **cs\_endValueSelector** (const CSvalueSelector\* vs, int *index*, CSint\*\* *vars*, void\* *pData*)

Finilize a process of domain reduction for variable at *index* in array *vars* having *size* elements. *pData* is pointer to arbitrary data can store pointer or int.

Returns TRUE if succeeded.

IZBOOL **cs\_selectValue** (CSint\* *v*, const CSvalueSelection\* *vs*)

Apply domain reduction stored in *vs* to CSint variable *v*.

Returns TRUE if succeeded.

## 7.7 Management of NoGood

`cs_searchValueSelectorRestartNG()` records failed variable-value combination into CSnoGoodSet variable as **NoGood**.

```
CSnoGoodSet* cs_createNoGoodSet (CSint** vars, int size, IZBOOL (*prefilter)(CSnoGoodSet* ngs,
                                                                              CSnoGood* ng, CSint** vars, int size, void* ext), int maxNo-
                                                                              Good,void(*destructorNotify)(CSnoGoodSet* ngs, void* ext),
                                                                              void* ext)
```

Create a area to record NoGoods.

- *vars* : Array of CSint variable for search function.
- *size* : Sizeof array *vars*
- *prefilter* : Function to decide whether record NoGood into this CSnoGoodSet variable.
- *maxNoGood* : Maximum count of NoGoods recorded in this CSnoGoodSet variable.
- *destructorNotify* : Created CSnoGoodSet variable is released automatically when context is restored. *destructorNotify* is called when this variable is released. Specify NULL if this functionality is not needed.
- *ext* :Passed to *prefilter* and *destructorNotify*.

*prefilter* is called with:

- *ngs* : Variable created with this call of `cs_createNoGoodSet()`
- *ng* : Pointer to NoGood.
- *vars*, *size* and *ext* : Same as this call of `cs_createNoGoodSet()`

*destructorNotify* is called with:

- *ngs* : Variable created with this call of `cs_createNoGoodSet()`
- *vars*, *size* and *ext* : Same as this call of `cs_createNoGoodSet()`

```
int cs_getNbNoGoods (CSnoGoodSet* ngs)
```

Returns count of NoGoods in *ngs*.

```
int cs_getNbNoGoodElements (CSnoGood* ng)
```

Returns count of elements in NoGood *ng*. Elements can be retrieved using `c:func:cs_getNoGoodElementAt`.

```
void cs_getNoGoodElementAt (int* pIndex, CSvalueSelection* vs, CSnoGood* ng, int index)
```

Get information of element at *index* in *ng*.

- *pIndex*: Position in the array *vars* passed to `cs_createNoGoodSet()`
- *vs*: Failed domain reduction

```
void cs_filterNoGood (CSnoGoodSet* ngs, IZBOOL (*filter)(CSnoGoodSet* ngs, CSnoGood* elem,
                                                         CSint** vars, int size, void* ext), void* ext)
```

Scan NoGoods registered in *ngs* and remove NoGoods which *filter* returns FALSE. Parameteres for *filter* is same as *prefilter* of `cs_createNoGoodSet()`.

```
void cs_addNoGood (CSnoGoodSet* ngs, int* index, CSvalueSelection* vs, int size)
```

Add a NoGood to *ngs*. *index* is an array of index of variable and *vs* is an array of CSvalueSelection. *size* is size of these arrays.

```
void cs_setMaxNbNoGoods (CSnoGoodSet* ngs, int max)
```

Set max count of NoGoods stored in *ngs*.

## 7.8 Notifications of Search state

Search functions which take `CSsearchNotify` type parameter can notify their state using callback functions.

`CSsearchNotify* cs_createSearchNotify (void* ext)`

Create `SearchNotify` type variable to pass to search function. *ext* will be passed to callback functions.

Created variable must be released using `cs_freeSearchNotify()`.

`void cs_freeSearchNotify (CSsearchNotify* notify)`

Release a variable created using `cs_createSearchNotify()`.

`void cs_searchNotifySetSearchStart (CSsearchNotify* notify, void (*searchStart)(int maxFails, CSint** allvars, int nbVars, void* ext))`

Register a function *searchStart* called when start of search.

In `cs_searchValueSelectorRestartNG()`, *searchStart* will be called at every restart.

Following parameters are passed to *searchStart*.

- *maxFails* : Maximum fails allowed to starting search
- *allvars* : Array of `CSint` for search function
- *nbVars* : Size of *allvars*
- *ext* : Pointer passed to `cs_createSearchNotify()`

`void cs_searchNotifySetSearchEnd (CSsearchNotify* notify, void (*searchEnd)(IZBOOL result, int nbFails, int maxFails, CSint** allvars, int nbVars, void* ext))`

Register a function *searchEnd* called when search is done..

In `cs_searchValueSelectorRestartNG()`, *searchEnd* will be called at every end of restart.

Following parameters are passed to *searchEnd*.

- *result* : TRUE when solution is found. Otherwise FALSE
- *nbFails* : Count of fails occurred while this search
- *maxFails* : Maximum fails allowed to this search
- *allvars* : Array of `CSint` for search function
- *nbVars* : Size of *allvars*
- *ext* : Pointer passed to `cs_createSearchNotify()`

`void cs_searchNotifySetBeforeValueSelection (CSsearchNotify* notify, void (*beforeValueSelection)(int depth, int index, const CSvalueSelection* vs, CSint** allvars, int nbVars, void* ext))`

Register a function *beforeValueSelection* called before domain reduction is applied to `CSint` variable.

Following parameters are passed to *beforeValueSelection*.

- *depth* : Depth of search
- *index* : Index of variable in *allvars*
- *vs* : Method of domain reduction.
- *allvars* : Array of `CSint` for search function
- *nbVars* : Size of *allvars*
- *ext* : Pointer passed to `cs_createSearchNotify()`

```
void cs_searchNotifySetAfterValueSelection (CSsearchNotify* notify, void (*afterValueSe-  
                                         lection)(IZBOOL result, int depth, int index,  
                                         const CSvalueSelection* vs, CSint** allvars, int  
                                         nbVars, void* ext))
```

Register a function *afterValueSelection* called after domain reduction is applied to CSint variable. Following parameters are passed to *afterValueSelection*.

- *result* : TRUE if domain reductions is done successfully. Otherwise FALSE
- *depth* : Depth of search
- *index* : Index of variable in *allvars*
- *vs* : Method of domain reduction.
- *allvars* : Array of CSint for search function
- *nbVars* : Size of *allvars*
- *ext* : Pointer passed to *cs\_createSearchNotify()*

```
void cs_searchNotifySetEnter (CSsearchNotify* notify, void (*enter)(int depth, int index, CSint** al-  
                                         lvars, int nbVars, void* ext))
```

Register a function *enter* called when CSint variable is selected to reduce its domain.

Following parameters are passed to *enter*.

- *depth* : Depth of search
- *index* : Index of selected variable in *allvars*
- *allvars* : Array of CSint for search function
- *nbVars* : Size of *allvars*
- *ext* : Pointer passed to *cs\_createSearchNotify()*

```
void cs_searchNotifySetLeave (CSsearchNotify* notify, void (*leave)(int depth, int index, CSint** al-  
                                         lvars, int nbVars, void* ext))
```

Register a function *leave* called after all reduction methods are tried to CSint variable.

Following parameters are passed to *leave*.

- *depth* : Depth of search
- *index* : Index of selected variable in *allvars*
- *allvars* : Array of CSint for search function
- *nbVars* : Size of *allvars*
- *ext* : Pointer passed to *cs\_createSearchNotify()*

```
void cs_searchNotifySetFound (CSsearchNotify* notify, IZBOOL (*found)(int depth, CSint** allvars,  
                                         int nbVars, void* ext))
```

Register a function *found* called when a solution is found.

Following parameters are passed to *found*.

- *depth* : Depth of search
- *allvars* : Array of CSint for search function
- *nbVars* : Size of *allvars*
- *ext* : Pointer passed to *cs\_createSearchNotify()*

If *found* returns TRUE, search function ends with return value TRUE. Otherwise search will be continued.  
This callback is called multiple time on same solution when search function uses restart.



## DEMON

During constraint propagation, some events (i.e. changes in CSint variables domains) will occur on CSint variables. These events are categorized into four exclusive types:

**Known:** the domain has been reduced to one value (the CSint variable is instantiated);

Ex.: `cs_EQ(vint, 0);` /\* raise a Known event \*/

**NewMin:** the minimum value of the domain has been changed (became strictly greater);

Ex.: `cs_GT(vint, 0);`

**NewMax:** the maximum value of the domain has been changed (became strictly lower);

Ex.: `cs_LT(vint, 0);`

**Neq:** one value has been removed from the domain;

Ex.: `cs_NEQ(vint, 0);`

These events are exclusive, that is:

- a known event will not raise neither a newMin, newMax, nor a neq event;
- newMin nor newMax events will not raise any neq event;

For example,

```
CSint *vint = cs_createCSint(0, 10);
cs_GE(vint, 10);
```

will raise a known event (*vint* will be instantiated to 10) but not a newMin event.

```
CSint *vint = cs_createCSint(0, 10);
cs_NEQ(vint, 0);
```

will raise a newMin event (*vint* will be strictly greater than 1), but not a neq event.

**IZBOOL cs\_eventAllKnown** (CSint \*\*array, int size, IZBOOL (\*allKnown)(CSint \*\*array, int size, void \*extra), void \*extra)

The function *allKnown()* will be called when all the CSint variables referenced by *array* are instantiated (i.e. known).

In the case where all the CSint variables referenced by *array* are instantiated when *cs\_eventAllKnown()* is called, it returns the result of the *allKnown()* call, otherwise it returns TRUE.

The *extra* argument is a pointer to a void variable that can be used freely.

Each time *allKnown()* is called, this *extra* value is passed.

IZBOOL **cs\_eventKnown** (CSint \*\*array, int size, IZBOOL (\*known)(int val, int index, CSint \*\*array, int size, void \*extra), void \*extra)

The function *known()* will be called when an *array* [ *index* ] CSint variable is instantiated.

The *extra* argument is a pointer to a void variable that can be used freely.

Each time *known()* is called, this *\*extra* value is passed.

void **cs\_eventNewMin** (CSint \*\*array, int size, IZBOOL (\*newMin)(CSint \*vint, int index, int oldMin, CSint \*\*array, int size, void \*extra), void \*extra)

The function *newMin()* will be called each time when the minimum value of *array* [ *index* ] CSint variable is increased.

The *extra* argument is a pointer to a void variable that can be used freely.

Each time *newMin()* is called, this *extra* value is passed.

void **cs\_eventNewMax** (CSint \*\*array, int size, IZBOOL (\*newMax)(CSint \*vint, int index, int oldMax, CSint \*\*array, int size, void \*extra), void \*extra)

The function *newMax()* will be called each time when the maximum value of *array* [ *index* ] CSint variable is decreased.

The *extra* argument is a pointer to a void variable that can be used freely.

Each time *newMax()* is called, this *extra* value is passed.

void **cs\_eventNeq** (CSint \*\*array, int size, IZBOOL (\*neq)(CSint \*vint, int index, int neqValue, CSint \*\*array, int size, void \*extra), void \*extra)

The function *neq()* will be called each time when a value is removed from the *array* [ *index* ] CSint variable.

The *extra* argument is a pointer to a void variable that can be used freely.

Each time *neq()* is called, this *extra* value is passed.

void **cs\_backtrack** (CSint \*vint, int i, void (\*backtrack)(CSint \*vint, int i))

The function *backtrack()* is called when context is restored.

*vint* and *i* given to *cs\_backtrack* are passed to *backtrack()*.

void **cs\_backtrackExt** (CSint \*vint, void\* ext, void (\*backtrack)(CSint \*vint, void \*ext))

The function *backtrack()* is called when context is restored.

*vint* and *ext* given to *cs\_backtrack* are passed to *backtrackExt()*.

void **cs\_eventConflict** (CSint \*\*array, int size, void (\*conflict)(CSint \*vint, int index, const CSvalueSe-  
lection\* vs, CSint \*\*array, int size, void \*extra), void \*extra)

The function *conflict()* is called when constraint propagation from a variable in the array is failed.

The *extra* argument is a pointer to a void variable that can be used freely.

Following parameters are passed to *conflict()*.

- *vint, index* : Pointer to a variable and index of a variable in the *array*.
- *vs* : Opration on a variable

Other parameters are same as passed to *cs\_eventConflict()*.

## CONTEXT

The following functions give an access to the heap where all the information on the events that had occurred on all the CSint variables created.

By events we mean changes in the domains of the CSint variables (like known, newMin, newMax, neq) caused by Constraint Propagation or constraint settings.

These functions will be used to create your own generation function, but are not needed when the primitives like `cs_search()` are used.

int **cs\_saveContext** ()

Saves the context, i.e. the domains and the constraints of all the CSint variables that are available when the call is made.

It returns an integer *label* used to call functions such as `cs_forgetSaveContextUntil()`, `cs_acceptContextUntil()` or `cs_restoreContextUntil()` take an integer *label* parameter.

void **cs\_forgetSaveContext** ()

Cancels the last `cs_saveContext()` call. This functions should be used instead of `cs_acceptContext()` inside `cs_event*` functions.

void **cs\_restoreAndSaveContext** ()

The context is restored as same as before the last `cs_saveContext()` call, and `cs_saveContext()` is called again.

void **cs\_acceptContext** ()

All the changes made on the CSint variables since the last `cs_saveContext()` call are accepted (i.e., this context cannot be restored any more). This function frees the memory of the heap since the last `cs_saveContext()` call.

As it cuts possible backtrack until the last `cs_saveContext()` call, `cs_acceptContext()` should not be called inside a `cs_event*` functions.

void **cs\_acceptAll** ()

All the changes made on the CSint variables since the first `cs_saveContext()` call are accepted. This function frees all the memory of the heap.

void **cs\_restoreContext** ()

The context is restored as same as before the last `cs_saveContext()` call.

void **cs\_restoreAll** ()

The context is restored as same as before the first `cs_saveContext()` call.

These following functions take an integer *label* as an argument. This *label* must be an integer returned by `cs_saveContext()`.

void **cs\_forgetSaveContextUntil** (int *label*)

Cancels the all the `cs_saveContext()` calls until the one referenced by *label*.

void **cs\_acceptContextUntil** (int *label*)

All the changes made on the CSint variables since the `cs_saveContext()` call referenced by *label* are accepted (i.e., this context cannot be restored any more). This function frees the memory of the heap since the `cs_saveContext()` call referenced by *label*.

void **cs\_restoreContextUntil** (int *label*)

The context is restored as same as before the `cs_saveContext()` call referenced by *label*.

Ex: the `cs_search()` procedure could be implemented as follows:

```
IZBOOL cs_search(CSint **allvars, int nbVars, CSint* (*findFreeVar)(CSint **allvars,
↪int nbVars)) {
    CSint *var = findFreeVar(allvars, nbVars);
    if (var) {
        int val;
        cs_saveContext();

        for (val = cs_getMin(var); val <= cs_getMax(var); val = cs_getNextValue(var,
↪val)) {
            if (cs_EQ(var, val) && cs_search(allvars, nbVars, findFreeVar))
                return TRUE;

            cs_restoreAndSaveContext();
        }

        cs_acceptContext();
        return FALSE;
    }
    else {
        return TRUE;
    }
}
```

## C

- `cs_Abs` (*C function*), 10
- `cs_acceptAll` (*C function*), 29
- `cs_acceptContext` (*C function*), 29
- `cs_acceptContextUntil` (*C function*), 29
- `cs_Add` (*C function*), 9
- `cs_addNoGood` (*C function*), 22
- `cs_AllNeq` (*C function*), 11
- `cs_backtrack` (*C function*), 28
- `cs_backtrackExt` (*C function*), 28
- `cs_cancelSearch` (*C function*), 19
- `cs_createCSint` (*C function*), 5
- `cs_createCSintArray` (*C function*), 5
- `cs_createCSintFromDomain` (*C function*), 5
- `cs_createNamedCSint` (*C function*), 5
- `cs_createNoGoodSet` (*C function*), 22
- `cs_createSearchNotify` (*C function*), 23
- `cs_createValueSelector` (*C function*), 20
- `cs_Cumulative` (*C function*), 14
- `cs_Disjunctive` (*C function*), 14
- `cs_Div` (*C function*), 9
- `cs_Element` (*C function*), 13
- `cs_end` (*C function*), 3
- `cs_endValueSelector` (*C function*), 21
- `cs_Eq` (*C function*), 11
- `CS_ERR_GETVALUE` (*C macro*), 3
- `CS_ERR_NO_MEMORY` (*C macro*), 3
- `CS_ERR_NONE` (*C macro*), 3
- `CS_ERR_OVERFLOW` (*C macro*), 3
- `cs_eventAllKnown` (*C function*), 27
- `cs_eventConflict` (*C function*), 28
- `cs_eventKnown` (*C function*), 27
- `cs_eventNeq` (*C function*), 28
- `cs_eventNewMax` (*C function*), 28
- `cs_eventNewMin` (*C function*), 28
- `cs_filterNoGood` (*C function*), 22
- `cs_findAll` (*C function*), 18
- `cs_findFreeVar` (*C function*), 15
- `cs_findFreeVarNbConstraints` (*C function*), 15
- `cs_findFreeVarNbElements` (*C function*), 15
- `cs_findFreeVarNbElementsMin` (*C function*), 15
- `cs_forgetSaveContext` (*C function*), 29
- `cs_forgetSaveContextUntil` (*C function*), 29
- `cs_fprintf` (*C function*), 6
- `cs_fprintStats` (*C function*), 4
- `cs_freeDomain` (*C function*), 6
- `cs_freeSearchNotify` (*C function*), 23
- `cs_freeValueSelector` (*C function*), 20
- `cs_Ge` (*C function*), 11
- `cs_getDomain` (*C function*), 6
- `cs_getErr` (*C function*), 3
- `cs_getMax` (*C function*), 5
- `cs_getMin` (*C function*), 5
- `cs_getName` (*C function*), 5
- `cs_getNbChoicePoints` (*C function*), 16
- `cs_getNbConstraints` (*C function*), 5
- `cs_getNbElements` (*C function*), 5
- `cs_getNbFails` (*C function*), 16
- `cs_getNbNoGoodElements` (*C function*), 22
- `cs_getNbNoGoods` (*C function*), 22
- `cs_getNextValue` (*C function*), 6
- `cs_getNoGoodElementAt` (*C function*), 22
- `cs_getPreviousValue` (*C function*), 6
- `cs_getValue` (*C function*), 6
- `cs_getValueSelector` (*C function*), 19
- `cs_getVersion` (*C function*), 4
- `cs_Gt` (*C function*), 11
- `cs_IfEq` (*C function*), 13
- `cs_IfNeq` (*C function*), 13
- `cs_InArray` (*C function*), 7
- `cs_Index` (*C function*), 13
- `cs_InInterval` (*C function*), 7
- `cs_init` (*C function*), 3
- `cs_initErr` (*C function*), 3
- `cs_initValueSelector` (*C function*), 21
- `cs_isFree` (*C function*), 6
- `cs_isIn` (*C function*), 6
- `cs_isInstantiated` (*C function*), 6
- `cs_Le` (*C function*), 11
- `cs_Lt` (*C function*), 11
- `cs_Max` (*C function*), 13
- `cs_Min` (*C function*), 13
- `cs_minimize` (*C function*), 18
- `cs_Mul` (*C function*), 9

`cs_Neq` (*C function*), 11  
`cs_NotInArray` (*C function*), 7  
`cs_NotInInterval` (*C function*), 7  
`cs_Occur` (*C function*), 13  
`cs_OccurConstraints` (*C function*), 13  
`cs_OccurDomain` (*C function*), 13  
`cs_printf` (*C function*), 6  
`cs_printStats` (*C function*), 4  
`cs_Regular` (*C function*), 14  
`cs_ReifEq` (*C function*), 12  
`cs_ReifGe` (*C function*), 12  
`cs_ReifGt` (*C function*), 12  
`cs_ReifLe` (*C function*), 12  
`cs_ReifLt` (*C function*), 12  
`cs_ReifNeq` (*C function*), 12  
`cs_restoreAll` (*C function*), 29  
`cs_restoreAndSaveContext` (*C function*), 29  
`cs_restoreContext` (*C function*), 29  
`cs_restoreContextUntil` (*C function*), 30  
`cs_saveContext` (*C function*), 29  
`cs_ScalProd` (*C function*), 9  
`cs_search` (*C function*), 15  
`cs_searchCriteria` (*C function*), 16  
`cs_searchCriteriaFail` (*C function*), 17  
`cs_searchFail` (*C function*), 17  
`cs_searchMatrix` (*C function*), 17  
`cs_searchMatrixFail` (*C function*), 18  
`cs_searchNotifySetAfterValueSelection`  
    (*C function*), 23  
`cs_searchNotifySetBeforeValueSelection`  
    (*C function*), 23  
`cs_searchNotifySetEnter` (*C function*), 24  
`cs_searchNotifySetFound` (*C function*), 24  
`cs_searchNotifySetLeave` (*C function*), 24  
`cs_searchNotifySetSearchEnd` (*C function*), 23  
`cs_searchNotifySetSearchStart` (*C function*),  
    23  
`cs_searchValueSelectorFail` (*C function*), 17  
`cs_searchValueSelectorRestartNG` (*C func-*  
    *tion*), 17  
`cs_selectNextValue` (*C function*), 21  
`cs_selectValue` (*C function*), 21  
`cs_setErr` (*C function*), 3  
`cs_setErrHandler` (*C function*), 4  
`cs_setMaxNbNoGoods` (*C function*), 22  
`cs_setName` (*C function*), 6  
`cs_Sigma` (*C function*), 9  
`cs_Sub` (*C function*), 9  
`cs_VAdd` (*C function*), 9  
`CS_VALUE_SELECTION_EQ` (*C macro*), 21  
`CS_VALUE_SELECTION_GE` (*C macro*), 21  
`CS_VALUE_SELECTION_GT` (*C macro*), 21  
`CS_VALUE_SELECTION_LE` (*C macro*), 21  
`CS_VALUE_SELECTION_LT` (*C macro*), 21  
`CS_VALUE_SELECTION_NEQ` (*C macro*), 21  
`CS_VALUE_SELECTOR_LOWER_AND_UPPER` (*C*  
    *macro*), 19  
`CS_VALUE_SELECTOR_MAX_TO_MIN` (*C macro*), 19  
`CS_VALUE_SELECTOR_MEDIAN_AND_REST` (*C*  
    *macro*), 20  
`CS_VALUE_SELECTOR_MIN_TO_MAX` (*C macro*), 19  
`CS_VALUE_SELECTOR_UPPER_AND_LOWER` (*C*  
    *macro*), 20  
`cs_VarElement` (*C function*), 13  
`cs_VarElementRange` (*C function*), 13  
`cs_VDiv` (*C function*), 9  
`cs_VMax` (*C function*), 13  
`cs_VMin` (*C function*), 13  
`cs_VMul` (*C function*), 9  
`cs_VScalProd` (*C function*), 9  
`cs_Vsearch` (*C function*), 15  
`cs_VSub` (*C function*), 9  
`CSINT` (*C function*), 5  
`CSvalueSelection` (*C type*), 21

I

`IZ_VERSION_MAJOR` (*C macro*), 4  
`IZ_VERSION_MINOR` (*C macro*), 4  
`IZ_VERSION_PATCH` (*C macro*), 4